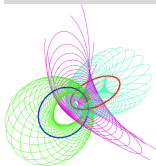


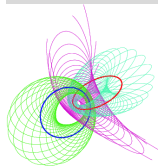
Path integrals for quadratic Lagrangians on real, p -adic, and adelic spaces

joint work with B. Dragovich

*The Third International Conference on p -Adic Mathematical
Physics*, – Moscow, October 1-6, 2007,

Zoran Rakić
Faculty of Mathematics
University of Belgrade, Serbia





Formalisms of classical mechanics:

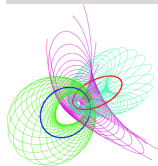
- Hamilton
- Lagrange

Formalisms of quantum mechanics:

- Heisenberg: $i\hbar \frac{d\hat{A}}{dt} = i\hbar \frac{\partial \hat{A}}{\partial t} + [\hat{A}, \hat{H}],$
- Schrödinger: $i\hbar \frac{\partial \Psi(x, t)}{\partial t} = H(\hat{k}, x)\Psi(x, t), \quad \hat{k} = -i\hbar \frac{\partial}{\partial x}.$
- Feynman:

$$\mathcal{K}(x'', t''; x', t') = \int_{x', t'}^{x'', t''} \exp\left(\frac{2\pi i}{h} \int_{t'}^{t''} L(\dot{q}, q, t) dt\right) \mathcal{D}q,$$

where $\int_{t'}^{t''} L(\dot{q}, q, t) dt = S[q]$



Formalisms of classical mechanics:

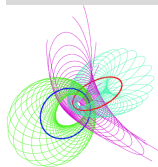
- Hamilton
- Lagrange

Formalisms of quantum mechanics:

- Heisenberg: $i\hbar \frac{d\hat{A}}{dt} = i\hbar \frac{\partial \hat{A}}{\partial t} + [\hat{A}, \hat{H}],$
- Schrödinger: $i\hbar \frac{\partial \Psi(x, t)}{\partial t} = H(\hat{k}, x)\Psi(x, t), \quad \hat{k} = -i\hbar \frac{\partial}{\partial x}.$
- Feynman:

$$\mathcal{K}(x'', t''; x', t') = \int_{x', t'}^{x'', t''} \exp\left(\frac{2\pi i}{h} \int_{t'}^{t''} L(\dot{q}, q, t) dt\right) \mathcal{D}q,$$

where $\int_{t'}^{t''} L(\dot{q}, q, t) dt = S[q]$



Formalisms of classical mechanics:

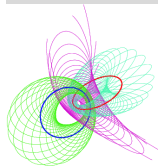
- Hamilton
- Lagrange

Formalisms of quantum mechanics:

- Heisenberg: $i\hbar \frac{d\hat{A}}{dt} = i\hbar \frac{\partial \hat{A}}{\partial t} + [\hat{A}, \hat{H}]$,
- Schrödinger: $i\hbar \frac{\partial \Psi(x, t)}{\partial t} = H(\hat{k}, x)\Psi(x, t)$, $\hat{k} = -i\hbar \frac{\partial}{\partial x}$.
- Feynman:

$$\mathcal{K}(x'', t''; x', t') = \int_{x', t'}^{x'', t''} \exp\left(\frac{2\pi i}{h} \int_{t'}^{t''} L(\dot{q}, q, t) dt\right) \mathcal{D}q,$$

where $\int_{t'}^{t''} L(\dot{q}, q, t) dt = S[q]$



Formalisms of classical mechanics:

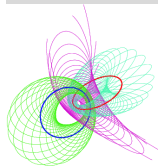
- Hamilton
- Lagrange

Formalisms of quantum mechanics:

- Heisenberg: $i\hbar \frac{d\hat{A}}{dt} = i\hbar \frac{\partial \hat{A}}{\partial t} + [\hat{A}, \hat{H}],$
- Schrödinger: $i\hbar \frac{\partial \Psi(x, t)}{\partial t} = H(\hat{k}, x)\Psi(x, t), \quad \hat{k} = -i\hbar \frac{\partial}{\partial x}.$
- Feynman:

$$\mathcal{K}(x'', t''; x', t') = \int_{x', t'}^{x'', t''} \exp\left(\frac{2\pi i}{h} \int_{t'}^{t''} L(\dot{q}, q, t) dt\right) \mathcal{D}q,$$

where $\int_{t'}^{t''} L(\dot{q}, q, t) dt = S[q]$



Formalisms of classical mechanics:

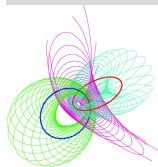
- Hamilton
- Lagrange

Formalisms of quantum mechanics:

- Heisenberg: $i\hbar \frac{d\hat{A}}{dt} = i\hbar \frac{\partial \hat{A}}{\partial t} + [\hat{A}, \hat{H}]$,
- Schrödinger: $i\hbar \frac{\partial \Psi(x, t)}{\partial t} = H(\hat{k}, x)\Psi(x, t)$, $\hat{k} = -i\hbar \frac{\partial}{\partial x}$.
- Feynman:

$$\mathcal{K}(x'', t''; x', t') = \int_{x', t'}^{x'', t''} \exp\left(\frac{2\pi i}{h} \int_{t'}^{t''} L(\dot{q}, q, t) dt\right) \mathcal{D}q,$$

where $\int_{t'}^{t''} L(\dot{q}, q, t) dt = S[q]$



Formalisms of classical mechanics:

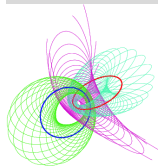
- Hamilton
- Lagrange

Formalisms of quantum mechanics:

- Heisenberg: $i\hbar \frac{d\hat{A}}{dt} = i\hbar \frac{\partial \hat{A}}{\partial t} + [\hat{A}, \hat{H}],$
- Schrödinger: $i\hbar \frac{\partial \Psi(x, t)}{\partial t} = H(\hat{k}, x)\Psi(x, t), \quad \hat{k} = -i\hbar \frac{\partial}{\partial x}.$
- Feynman:

$$\mathcal{K}(x'', t''; x', t') = \int_{x', t'}^{x'', t''} \exp\left(\frac{2\pi i}{h} \int_{t'}^{t''} L(\dot{q}, q, t) dt\right) \mathcal{D}q,$$

where $\int_{t'}^{t''} L(\dot{q}, q, t) dt = S[q]$



Formalisms of classical mechanics:

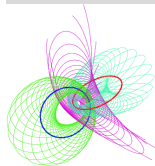
- Hamilton
- Lagrange

Formalisms of quantum mechanics:

- Heisenberg: $i\hbar \frac{d\hat{A}}{dt} = i\hbar \frac{\partial \hat{A}}{\partial t} + [\hat{A}, \hat{H}],$
- Schrödinger: $i\hbar \frac{\partial \Psi(x, t)}{\partial t} = H(\hat{k}, x)\Psi(x, t), \quad \hat{k} = -i\hbar \frac{\partial}{\partial x}.$
- Feynman:

$$\mathcal{K}(x'', t''; x', t') = \int_{x', t'}^{x'', t''} \exp\left(\frac{2\pi i}{h} \int_{t'}^{t''} L(\dot{q}, q, t) dt\right) \mathcal{D}q,$$

where $\int_{t'}^{t''} L(\dot{q}, q, t) dt = S[q]$



Formalisms of classical mechanics:

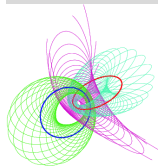
- Hamilton
- Lagrange

Formalisms of quantum mechanics:

- Heisenberg:
$$i\hbar \frac{d\hat{A}}{dt} = i\hbar \frac{\partial \hat{A}}{\partial t} + [\hat{A}, \hat{H}],$$
- Schrödinger:
$$i\hbar \frac{\partial \Psi(x, t)}{\partial t} = H(\hat{k}, x)\Psi(x, t), \quad \hat{k} = -i\hbar \frac{\partial}{\partial x}.$$
- Feynman:

$$\mathcal{K}(x'', t''; x', t') = \int_{x', t'}^{x'', t''} \exp\left(\frac{2\pi i}{h} \int_{t'}^{t''} L(\dot{q}, q, t) dt\right) \mathcal{D}q,$$

where
$$\int_{t'}^{t''} L(\dot{q}, q, t) dt = S[q]$$



Formalisms of classical mechanics:

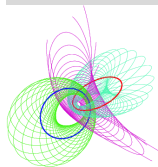
- Hamilton
- Lagrange

Formalisms of quantum mechanics:

- Heisenberg:
$$i\hbar \frac{d\hat{A}}{dt} = i\hbar \frac{\partial \hat{A}}{\partial t} + [\hat{A}, \hat{H}],$$
- Schrödinger:
$$i\hbar \frac{\partial \Psi(x, t)}{\partial t} = H(\hat{k}, x)\Psi(x, t), \quad \hat{k} = -i\hbar \frac{\partial}{\partial x}.$$
- Feynman:

$$\mathcal{K}(x'', t''; x', t') = \int_{x', t'}^{x'', t''} \exp\left(\frac{2\pi i}{h} \int_{t'}^{t''} L(\dot{q}, q, t) dt\right) \mathcal{D}q,$$

where $\int_{t'}^{t''} L(\dot{q}, q, t) dt = S[q]$



Formalisms of classical mechanics:

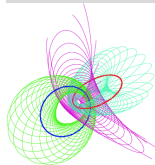
- Hamilton
- Lagrange

Formalisms of quantum mechanics:

- Heisenberg: $i\hbar \frac{d\hat{A}}{dt} = i\hbar \frac{\partial \hat{A}}{\partial t} + [\hat{A}, \hat{H}],$
- Schrödinger: $i\hbar \frac{\partial \Psi(x, t)}{\partial t} = H(\hat{k}, x)\Psi(x, t), \quad \hat{k} = -i\hbar \frac{\partial}{\partial x}.$
- Feynman:

$$\mathcal{K}(x'', t''; x', t') = \int_{x', t'}^{x'', t''} \exp\left(\frac{2\pi i}{h} \int_{t'}^{t''} L(\dot{q}, q, t) dt\right) \mathcal{D}q,$$

where $\int_{t'}^{t''} L(\dot{q}, q, t) dt = S[q]$



The probability amplitude $\mathcal{K}(x'', t''; x', t')$ plays central role in the theory and has the following properties:

$$\int \mathcal{K}(x'', t''; x, t) \mathcal{K}(x, t; x', t') dx = \mathcal{K}(x'', t''; x', t'),$$

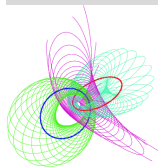
$$\int \bar{\mathcal{K}}(x'', t''; x', t') \mathcal{K}(y, t''; x', t') dx' = \delta(x'' - y),$$

$$\mathcal{K}(x'', t''; x', t'') = \lim_{t' \rightarrow t''} \mathcal{K}(x'', t''; x', t') = \delta(x'' - x'),$$

The Feynman's path integral method is appropriate for the generalizations to the p-adic case,

$$\mathcal{K}_p(x'', t''; x', t') = \int_{x', t'}^{x'', t''} \chi_p \left(-\frac{1}{h} \int_{t'}^{t''} L(\dot{q}, q, t) dt \right) \mathcal{D}q,$$

where $\chi_p(a)$ is p-adic additive character.



The probability amplitude $\mathcal{K}(x'', t''; x', t')$ plays central role in the theory and has the following properties:

$$\int \mathcal{K}(x'', t''; x, t) \mathcal{K}(x, t; x', t') dx = \mathcal{K}(x'', t''; x', t'),$$

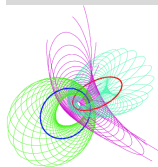
$$\int \bar{\mathcal{K}}(x'', t''; x', t') \mathcal{K}(y, t''; x', t') dx' = \delta(x'' - y),$$

$$\mathcal{K}(x'', t''; x', t'') = \lim_{t' \rightarrow t''} \mathcal{K}(x'', t''; x', t') = \delta(x'' - x'),$$

The Feynman's path integral method is appropriate for the generalizations to the p -adic case,

$$\mathcal{K}_p(x'', t''; x', t') = \int_{x', t'}^{x'', t''} \chi_p \left(-\frac{1}{h} \int_{t'}^{t''} L(\dot{q}, q, t) dt \right) \mathcal{D}q,$$

where $\chi_p(a)$ is p -adic additive character.



The probability amplitude $\mathcal{K}(x'', t''; x', t')$ plays central role in the theory and has the following properties:

$$\int \mathcal{K}(x'', t''; x, t) \mathcal{K}(x, t; x', t') dx = \mathcal{K}(x'', t''; x', t'),$$

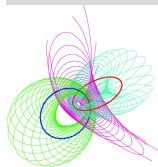
$$\int \bar{\mathcal{K}}(x'', t''; x', t') \mathcal{K}(y, t''; x', t') dx' = \delta(x'' - y),$$

$$\mathcal{K}(x'', t''; x', t'') = \lim_{t' \rightarrow t''} \mathcal{K}(x'', t''; x', t') = \delta(x'' - x'),$$

The Feynman's path integral method is appropriate for the generalizations to the p -adic case,

$$\mathcal{K}_p(x'', t''; x', t') = \int_{x', t'}^{x'', t''} \chi_p \left(-\frac{1}{h} \int_{t'}^{t''} L(\dot{q}, q, t) dt \right) \mathcal{D}q,$$

where $\chi_p(a)$ is p -adic additive character.



The probability amplitude $\mathcal{K}(x'', t''; x', t')$ plays central role in the theory and has the following properties:

$$\int \mathcal{K}(x'', t''; x, t) \mathcal{K}(x, t; x', t') dx = \mathcal{K}(x'', t''; x', t'),$$

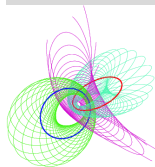
$$\int \bar{\mathcal{K}}(x'', t''; x', t') \mathcal{K}(y, t''; x', t') dx' = \delta(x'' - y),$$

$$\mathcal{K}(x'', t''; x', t'') = \lim_{t' \rightarrow t''} \mathcal{K}(x'', t''; x', t') = \delta(x'' - x'),$$

The Feynman's path integral method is appropriate for the generalizations to the p-adic case,

$$\mathcal{K}_p(x'', t''; x', t') = \int_{x', t'}^{x'', t''} \chi_p \left(-\frac{1}{h} \int_{t'}^{t''} L(\dot{q}, q, t) dt \right) \mathcal{D}q,$$

where $\chi_p(a)$ is p-adic additive character.



The **probability amplitude** $\mathcal{K}(x'', t''; x', t')$ plays central role in the theory and has the following properties:

$$\int \mathcal{K}(x'', t''; x, t) \mathcal{K}(x, t; x', t') dx = \mathcal{K}(x'', t''; x', t'),$$

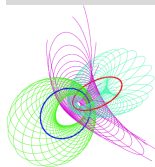
$$\int \bar{\mathcal{K}}(x'', t''; x', t') \mathcal{K}(y, t''; x', t') dx' = \delta(x'' - y),$$

$$\mathcal{K}(x'', t''; x', t'') = \lim_{t' \rightarrow t''} \mathcal{K}(x'', t''; x', t') = \delta(x'' - x'),$$

The Feynman's path integral method is appropriate for the generalizations to the p -adic case,

$$\mathcal{K}_p(x'', t''; x', t') = \int_{x', t'}^{x'', t''} \chi_p \left(-\frac{1}{h} \int_{t'}^{t''} L(\dot{q}, q, t) dt \right) \mathcal{D}q,$$

where $\chi_p(a)$ is p -adic additive character.



The probability amplitude $\mathcal{K}(x'', t''; x', t')$ plays central role in the theory and has the following properties:

$$\int \mathcal{K}(x'', t''; x, t) \mathcal{K}(x, t; x', t') dx = \mathcal{K}(x'', t''; x', t'),$$

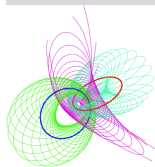
$$\int \bar{\mathcal{K}}(x'', t''; x', t') \mathcal{K}(y, t''; x', t') dx' = \delta(x'' - y),$$

$$\mathcal{K}(x'', t''; x', t'') = \lim_{t' \rightarrow t''} \mathcal{K}(x'', t''; x', t') = \delta(x'' - x'),$$

The Feynman's path integral method is appropriate for the generalizations to the p -adic case,

$$\mathcal{K}_p(x'', t''; x', t') = \int_{x', t'}^{x'', t''} \chi_p \left(-\frac{1}{h} \int_{t'}^{t''} L(\dot{q}, q, t) dt \right) \mathcal{D}q,$$

where $\chi_p(a)$ is p -adic additive character.



There is well defined Haar measure and integration, and we have

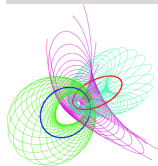
$$\int_{\mathbb{Q}_p} \chi_p(ayx) dx = \delta_p(ay) = |a|_p^{-1} \delta_p(y), \quad a \neq 0,$$

$$\int_{\mathbb{Q}_p} \chi_p(\alpha x^2 + \beta x) dx = \lambda_p(\alpha) |2\alpha|_p^{-\frac{1}{2}} \chi_p\left(-\frac{\beta^2}{4\alpha}\right), \quad \alpha \neq 0,$$

where $\delta_p(u)$ is the p -adic Dirac δ function, and for

$x = \sum_{k=m}^{+\infty} x_k p^k$, $x_k = 0, 1, \dots, p-1$, $x_m \neq 0$, we define $\lambda_p(x)$:

$$\lambda_p(x) = \begin{cases} 1, & m = 2j, \quad p \neq 2, \\ \left(\frac{x_m}{p}\right), & m = 2j+1, \quad p \equiv 1 \pmod{4}, \\ i \left(\frac{x_m}{p}\right), & m = 2j+1, \quad p \equiv 3 \pmod{4}, \end{cases}$$



Introduction

There is well defined Haar measure and integration, and we have

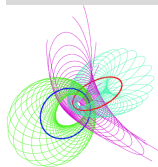
$$\int_{\mathbb{Q}_p} \chi_p(ayx) dx = \delta_p(ay) = |a|_p^{-1} \delta_p(y), \quad a \neq 0,$$

$$\int_{\mathbb{Q}_p} \chi_p(\alpha x^2 + \beta x) dx = \lambda_p(\alpha) |2\alpha|_p^{-\frac{1}{2}} \chi_p\left(-\frac{\beta^2}{4\alpha}\right), \quad \alpha \neq 0,$$

where $\delta_p(u)$ is the p -adic Dirac δ function, and for

$x = \sum_{k=m}^{+\infty} x_k p^k$, $x_k = 0, 1, \dots, p-1$, $x_m \neq 0$, we define $\lambda_p(x)$:

$$\lambda_p(x) = \begin{cases} 1, & m = 2j, \quad p \neq 2, \\ \left(\frac{x_m}{p}\right), & m = 2j+1, \quad p \equiv 1 \pmod{4}, \\ i \left(\frac{x_m}{p}\right), & m = 2j+1, \quad p \equiv 3 \pmod{4}, \end{cases}$$



Introduction

There is well defined Haar measure and integration, and we have

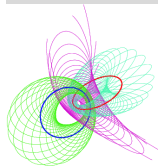
$$\int_{\mathbb{Q}_p} \chi_p(ayx) dx = \delta_p(ay) = |a|_p^{-1} \delta_p(y), \quad a \neq 0,$$

$$\int_{\mathbb{Q}_p} \chi_p(\alpha x^2 + \beta x) dx = \lambda_p(\alpha) |2\alpha|_p^{-\frac{1}{2}} \chi_p\left(-\frac{\beta^2}{4\alpha}\right), \quad \alpha \neq 0,$$

where $\delta_p(u)$ is the p -adic Dirac δ function, and for

$x = \sum_{k=m}^{+\infty} x_k p^k$, $x_k = 0, 1, \dots, p-1$, $x_m \neq 0$, we define $\lambda_p(x)$:

$$\lambda_p(x) = \begin{cases} 1, & m = 2j, \quad p \neq 2, \\ \left(\frac{x_m}{p}\right), & m = 2j + 1, \quad p \equiv 1 \pmod{4}, \\ i \left(\frac{x_m}{p}\right), & m = 2j + 1, \quad p \equiv 3 \pmod{4}, \end{cases}$$



There is well defined Haar measure and integration, and we have

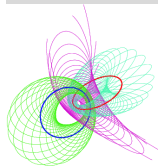
$$\int_{\mathbb{Q}_p} \chi_p(ayx) dx = \delta_p(ay) = |a|_p^{-1} \delta_p(y), \quad a \neq 0,$$

$$\int_{\mathbb{Q}_p} \chi_p(\alpha x^2 + \beta x) dx = \lambda_p(\alpha) |2\alpha|_p^{-\frac{1}{2}} \chi_p\left(-\frac{\beta^2}{4\alpha}\right), \quad \alpha \neq 0,$$

where $\delta_p(u)$ is the p -adic Dirac δ function, and for

$x = \sum_{k=m}^{+\infty} x_k p^k$, $x_k = 0, 1, \dots, p-1$, $x_m \neq 0$, we define $\lambda_p(x)$:

$$\lambda_p(x) = \begin{cases} 1, & m = 2j, \quad p \neq 2, \\ \left(\frac{x_m}{p}\right), & m = 2j+1, \quad p \equiv 1 \pmod{4}, \\ i \left(\frac{x_m}{p}\right), & m = 2j+1, \quad p \equiv 3 \pmod{4}, \end{cases}$$



Introduction

There is well defined Haar measure and integration, and we have

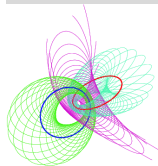
$$\int_{\mathbb{Q}_p} \chi_p(ayx) dx = \delta_p(ay) = |a|_p^{-1} \delta_p(y), \quad a \neq 0,$$

$$\int_{\mathbb{Q}_p} \chi_p(\alpha x^2 + \beta x) dx = \lambda_p(\alpha) |2\alpha|_p^{-\frac{1}{2}} \chi_p\left(-\frac{\beta^2}{4\alpha}\right), \quad \alpha \neq 0,$$

where $\delta_p(u)$ is the p -adic Dirac δ function, and for

$x = \sum_{k=m}^{+\infty} x_k p^k$, $x_k = 0, 1, \dots, p-1$, $x_m \neq 0$, we define $\lambda_p(x)$:

$$\lambda_p(x) = \begin{cases} 1, & m = 2j, \quad p \neq 2, \\ \left(\frac{x_m}{p}\right), & m = 2j + 1, \quad p \equiv 1 \pmod{4}, \\ i \left(\frac{x_m}{p}\right), & m = 2j + 1, \quad p \equiv 3 \pmod{4}, \end{cases}$$



There is well defined Haar measure and integration, and we have

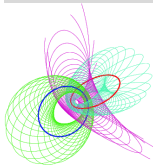
$$\int_{\mathbb{Q}_p} \chi_p(ax) dx = \delta_p(ay) = |a|_p^{-1} \delta_p(y), \quad a \neq 0,$$

$$\int_{\mathbb{Q}_p} \chi_p(\alpha x^2 + \beta x) dx = \lambda_p(\alpha) |2\alpha|_p^{-\frac{1}{2}} \chi_p\left(-\frac{\beta^2}{4\alpha}\right), \quad \alpha \neq 0,$$

where $\delta_p(u)$ is the p -adic Dirac δ function, and for

$x = \sum_{k=m}^{+\infty} x_k p^k$, $x_k = 0, 1, \dots, p-1$, $x_m \neq 0$, we define $\lambda_p(x)$:

$$\lambda_p(x) = \begin{cases} 1, & m = 2j, \quad p \neq 2, \\ \left(\frac{x_m}{p}\right), & m = 2j + 1, \quad p \equiv 1 \pmod{4}, \\ i \left(\frac{x_m}{p}\right), & m = 2j + 1, \quad p \equiv 3 \pmod{4}, \end{cases}$$



$$\lambda_2(x) = \begin{cases} \frac{1}{\sqrt{2}}[1 + (-1)^{x_{m+1}} i], & m = 2j, \\ \frac{1}{\sqrt{2}}(-1)^{x_{m+1} + x_{m+2}}[1 + (-1)^{x_{m+1}} i], & m = 2j + 1, \end{cases}$$

$\left(\frac{x_m}{p}\right)$ is the Legendre symbol,

$$\left(\frac{a}{p}\right) = \begin{cases} 1, & \text{if } a \equiv y^2 \pmod{p}, \\ -1, & \text{if } a \not\equiv y^2 \pmod{p}, \end{cases}$$

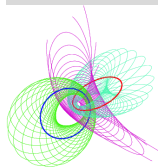
$$\lambda_p(a^2 x) = \lambda_p(x), \quad \lambda_p(x)\lambda_p(-x) = 1,$$

$$\lambda_p(x)\lambda_p(y) = \lambda_p(x+y)\lambda_p(x^{-1} + y^{-1}), \quad |\lambda_p(x)|_\infty = 1, \quad a \neq 0.$$

Definition

$$\text{Let } \Lambda_p(x_1, x_2, \dots, x_n) = \prod_{i=1}^n \lambda_p(x_i)$$

where subscript $p = \infty, 2, 3, \dots, p, \dots$.



$$\lambda_2(x) = \begin{cases} \frac{1}{\sqrt{2}}[1 + (-1)^{x_{m+1}} i], & m = 2j, \\ \frac{1}{\sqrt{2}}(-1)^{x_{m+1} + x_{m+2}}[1 + (-1)^{x_{m+1}} i], & m = 2j + 1, \end{cases}$$

$\left(\frac{x_m}{p}\right)$ is the Legendre symbol,

$$\left(\frac{a}{p}\right) = \begin{cases} 1, & \text{if } a \equiv y^2 \pmod{p}, \\ -1, & \text{if } a \not\equiv y^2 \pmod{p}, \end{cases}$$

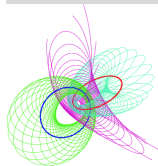
$$\lambda_p(a^2 x) = \lambda_p(x), \quad \lambda_p(x)\lambda_p(-x) = 1,$$

$$\lambda_p(x)\lambda_p(y) = \lambda_p(x+y)\lambda_p(x^{-1} + y^{-1}), \quad |\lambda_p(x)|_\infty = 1, \quad a \neq 0.$$

Definition

$$\text{Let } \Lambda_p(x_1, x_2, \dots, x_n) = \prod_{i=1}^n \lambda_p(x_i)$$

where subscript $p = \infty, 2, 3, \dots, p, \dots$.



$$\lambda_2(x) = \begin{cases} \frac{1}{\sqrt{2}}[1 + (-1)^{x_{m+1}} i], & m = 2j, \\ \frac{1}{\sqrt{2}}(-1)^{x_{m+1} + x_{m+2}}[1 + (-1)^{x_{m+1}} i], & m = 2j + 1, \end{cases}$$

$\left(\frac{x_m}{p}\right)$ is the Legendre symbol,

$$\left(\frac{a}{p}\right) = \begin{cases} 1, & \text{if } a \equiv y^2 \pmod{p}, \\ -1, & \text{if } a \not\equiv y^2 \pmod{p}, \end{cases}$$

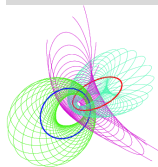
$$\lambda_p(a^2 x) = \lambda_p(x), \quad \lambda_p(x)\lambda_p(-x) = 1,$$

$$\lambda_p(x)\lambda_p(y) = \lambda_p(x+y)\lambda_p(x^{-1} + y^{-1}), \quad |\lambda_p(x)|_\infty = 1, \quad a \neq 0.$$

Definition

$$\text{Let } \Lambda_p(x_1, x_2, \dots, x_n) = \prod_{i=1}^n \lambda_p(x_i)$$

where subscript $p = \infty, 2, 3, \dots, p, \dots$.



$$\lambda_2(x) = \begin{cases} \frac{1}{\sqrt{2}}[1 + (-1)^{x_{m+1}} i], & m = 2j, \\ \frac{1}{\sqrt{2}}(-1)^{x_{m+1} + x_{m+2}}[1 + (-1)^{x_{m+1}} i], & m = 2j + 1, \end{cases}$$

$\left(\frac{x_m}{p}\right)$ is the Legendre symbol,

$$\left(\frac{a}{p}\right) = \begin{cases} 1, & \text{if } a \equiv y^2 \pmod{p}, \\ -1, & \text{if } a \not\equiv y^2 \pmod{p}, \end{cases}$$

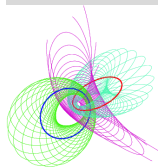
$$\lambda_p(a^2 x) = \lambda_p(x), \quad \lambda_p(x)\lambda_p(-x) = 1,$$

$$\lambda_p(x)\lambda_p(y) = \lambda_p(x+y)\lambda_p(x^{-1} + y^{-1}), \quad |\lambda_p(x)|_\infty = 1, \quad a \neq 0.$$

Definition

$$\text{Let } \Lambda_p(x_1, x_2, \dots, x_n) = \prod_{i=1}^n \lambda_p(x_i)$$

where subscript $p = \infty, 2, 3, \dots, p, \dots$.



$$\lambda_2(x) = \begin{cases} \frac{1}{\sqrt{2}}[1 + (-1)^{x_{m+1}} i], & m = 2j, \\ \frac{1}{\sqrt{2}}(-1)^{x_{m+1} + x_{m+2}}[1 + (-1)^{x_{m+1}} i], & m = 2j + 1, \end{cases}$$

$\left(\frac{x_m}{p}\right)$ is the Legendre symbol,

$$\left(\frac{a}{p}\right) = \begin{cases} 1, & \text{if } a \equiv y^2 \pmod{p}, \\ -1, & \text{if } a \not\equiv y^2 \pmod{p}, \end{cases}$$

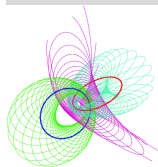
$$\lambda_p(a^2 x) = \lambda_p(x), \quad \lambda_p(x)\lambda_p(-x) = 1,$$

$$\lambda_p(x)\lambda_p(y) = \lambda_p(x+y)\lambda_p(x^{-1} + y^{-1}), \quad |\lambda_p(x)|_\infty = 1, \quad a \neq 0.$$

Definition

$$\text{Let } \Lambda_p(x_1, x_2, \dots, x_n) = \prod_{i=1}^n \lambda_p(x_i)$$

where subscript $p = \infty, 2, 3, \dots, p, \dots$.



$$\lambda_2(x) = \begin{cases} \frac{1}{\sqrt{2}}[1 + (-1)^{x_{m+1}} i], & m = 2j, \\ \frac{1}{\sqrt{2}}(-1)^{x_{m+1}+x_{m+2}}[1 + (-1)^{x_{m+1}} i], & m = 2j + 1, \end{cases}$$

$\left(\frac{x_m}{p}\right)$ is the Legendre symbol,

$$\left(\frac{a}{p}\right) = \begin{cases} 1, & \text{if } a \equiv y^2 \pmod{p}, \\ -1, & \text{if } a \not\equiv y^2 \pmod{p}, \end{cases}$$

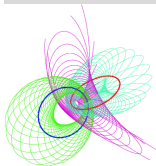
$$\lambda_p(a^2 x) = \lambda_p(x), \quad \lambda_p(x)\lambda_p(-x) = 1,$$

$$\lambda_p(x)\lambda_p(y) = \lambda_p(x+y)\lambda_p(x^{-1} + y^{-1}), \quad |\lambda_p(x)|_\infty = 1, \quad a \neq 0.$$

Definition

$$\text{Let } \Lambda_p(x_1, x_2, \dots, x_n) = \prod_{i=1}^n \lambda_p(x_i)$$

where subscript $p = \infty, 2, 3, \dots, p, \dots$.



Proposition

The functions $\Lambda_p(x_1, x_2, \dots, x_n)$ satisfy the properties

$$\Lambda_\infty(x_1, x_2, \dots, x_n) = \frac{1}{\sqrt{i^{n-1}}} \lambda_\infty(x_1 x_2 \cdots x_n),$$

$$\Lambda_p(x_1, x_2, \dots, x_n) = \prod_{i < j \leq n} (x_i, x_j)_p \lambda_p(x_1 x_2 \cdots x_n), \quad p \neq 2,$$

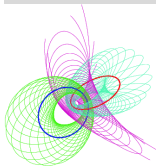
where $(x_i, x_j)_p$ is the Hilbert symbol.

$$(a, b)_p = \begin{cases} 1, & \text{if } ax^2 + by^2 = z^2 \text{ has a nontrivial solution in } \mathbb{Q}_p. \\ -1, & \text{if } ax^2 + by^2 = z^2 \text{ has only trivial solution in } \mathbb{Q}_p. \end{cases}$$

The Hilbert symbol satisfies

$$\lambda_p(a) \lambda_p(b) = (a, b)_p \lambda_p(ab) \quad \text{if } p \neq 2,$$

$$(a, b)_p = (b, a)_p, \quad (a, bc)_p = (a, b)_p (a, c)_p.$$



Proposition

The functions $\Lambda_p(x_1, x_2, \dots, x_n)$ satisfy the properties

$$\Lambda_\infty(x_1, x_2, \dots, x_n) = \frac{1}{\sqrt{i^{n-1}}} \lambda_\infty(x_1 x_2 \cdots x_n),$$

$$\Lambda_p(x_1, x_2, \dots, x_n) = \prod_{i < j \leq n} (x_i, x_j)_p \lambda_p(x_1 x_2 \cdots x_n), \quad p \neq 2,$$

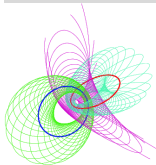
where $(x_i, x_j)_p$ is the Hilbert symbol.

$$(a, b)_p = \begin{cases} 1, & \text{if } ax^2 + by^2 = z^2 \text{ has a nontrivial solution in } \mathbb{Q}_p. \\ -1, & \text{if } ax^2 + by^2 = z^2 \text{ has only trivial solution in } \mathbb{Q}_p. \end{cases}$$

The Hilbert symbol satisfies

$$\lambda_p(a) \lambda_p(b) = (a, b)_p \lambda_p(ab) \quad \text{if } p \neq 2,$$

$$(a, b)_p = (b, a)_p, \quad (a, bc)_p = (a, b)_p (a, c)_p.$$



Proposition

The functions $\Lambda_p(x_1, x_2, \dots, x_n)$ satisfy the properties

$$\Lambda_\infty(x_1, x_2, \dots, x_n) = \frac{1}{\sqrt{i^{n-1}}} \lambda_\infty(x_1 x_2 \cdots x_n),$$

$$\Lambda_p(x_1, x_2, \dots, x_n) = \prod_{i < j \leq n} (x_i, x_j)_p \lambda_p(x_1 x_2 \cdots x_n), \quad p \neq 2,$$

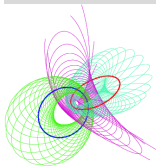
where $(x_i, x_j)_p$ is the Hilbert symbol.

$$(a, b)_p = \begin{cases} 1, & \text{if } ax^2 + by^2 = z^2 \text{ has a nontrivial solution in } \mathbb{Q}_p. \\ -1, & \text{if } ax^2 + by^2 = z^2 \text{ has only trivial solution in } \mathbb{Q}_p. \end{cases}$$

The Hilbert symbol satisfies

$$\lambda_p(a) \lambda_p(b) = (a, b)_p \lambda_p(ab) \quad \text{if } p \neq 2,$$

$$(a, b)_p = (b, a)_p, \quad (a, bc)_p = (a, b)_p (a, c)_p.$$



Proposition

The functions $\Lambda_p(x_1, x_2, \dots, x_n)$ satisfy the properties

$$\Lambda_\infty(x_1, x_2, \dots, x_n) = \frac{1}{\sqrt{i^{n-1}}} \lambda_\infty(x_1 x_2 \cdots x_n),$$

$$\Lambda_p(x_1, x_2, \dots, x_n) = \prod_{i < j \leq n} (x_i, x_j)_p \lambda_p(x_1 x_2 \cdots x_n), \quad p \neq 2,$$

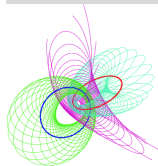
where $(x_i, x_j)_p$ is the Hilbert symbol.

$$(a, b)_p = \begin{cases} 1, & \text{if } ax^2 + by^2 = z^2 \text{ has a nontrivial solution in } \mathbb{Q}_p. \\ -1, & \text{if } ax^2 + by^2 = z^2 \text{ has only trivial solution in } \mathbb{Q}_p. \end{cases}$$

The Hilbert symbol satisfies

$$\lambda_p(a) \lambda_p(b) = (a, b)_p \lambda_p(ab) \quad \text{if } p \neq 2,$$

$$(a, b)_p = (b, a)_p, \quad (a, bc)_p = (a, b)_p (a, c)_p.$$



Proposition

Let $x = (x_1, x_2, \dots, x_n)$, $y = (y_1, y_2, \dots, y_n)$ be column vectors, and let $B = (B_{kl})$ be a nonsingular $n \times n$ matrix, where $x_k, y_k, B_{kl} \in \mathbb{Q}_v$. Then

$$\int_{\mathbb{Q}_v^n} \chi_p(y^T Bx) d^n x = |\det(B_{kl})|_p^{-1} \prod_{k=1}^n \delta_p(y_k),$$

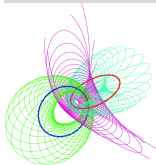
where y^T denotes transpose map of y .

Proposition

Let $x = (x_1, \dots, x_n)$, $\beta = (\beta_1, \dots, \beta_n)$ be two column vectors, and let $\alpha = (\alpha_{kl})$ be a nonsingular symmetric $n \times n$ matrix, where $x_k, \beta_k, \alpha_{kl} \in \mathbb{Q}_p$. Then

$$\begin{aligned} \int_{\mathbb{Q}_p^n} \chi_p(x^T \alpha x + \beta^T x) d^n x &= \Lambda_p(\alpha_1, \alpha_2, \dots, \alpha_n) |\det(2\alpha_{kl})|_p^{-\frac{1}{2}} \\ &\times \chi_p\left(-\frac{1}{4}\beta^T \alpha^{-1} \beta\right), \end{aligned}$$

where $\alpha_1, \alpha_2, \dots, \alpha_n$ are eigenvalues of the matrix α .



Proposition

Let $x = (x_1, x_2, \dots, x_n)$, $y = (y_1, y_2, \dots, y_n)$ be column vectors, and let $B = (B_{kl})$ be a nonsingular $n \times n$ matrix, where $x_k, y_k, B_{kl} \in \mathbb{Q}_v$. Then

$$\int_{\mathbb{Q}_v^n} \chi_p(y^T Bx) d^n x = |\det(B_{kl})|_p^{-1} \prod_{k=1}^n \delta_p(y_k),$$

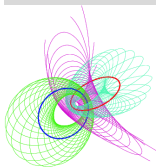
where y^T denotes transpose map of y .

Proposition

Let $x = (x_1, \dots, x_n)$, $\beta = (\beta_1, \dots, \beta_n)$ be two column vectors, and let $\alpha = (\alpha_{kl})$ be a nonsingular symmetric $n \times n$ matrix, where $x_k, \beta_k, \alpha_{kl} \in \mathbb{Q}_p$. Then

$$\int_{\mathbb{Q}_p^n} \chi_p(x^T \alpha x + \beta^T x) d^n x = \Lambda_p(\alpha_1, \alpha_2, \dots, \alpha_n) |\det(2\alpha_{kl})|_p^{-\frac{1}{2}} \\ \times \chi_p\left(-\frac{1}{4}\beta^T \alpha^{-1} \beta\right),$$

where $\alpha_1, \alpha_2, \dots, \alpha_n$ are eigenvalues of the matrix α .



Proposition

Let $x = (x_1, x_2, \dots, x_n)$, $y = (y_1, y_2, \dots, y_n)$ be column vectors, and let $B = (B_{kl})$ be a nonsingular $n \times n$ matrix, where $x_k, y_k, B_{kl} \in \mathbb{Q}_v$. Then

$$\int_{\mathbb{Q}_v^n} \chi_p(y^T Bx) d^n x = |\det(B_{kl})|_p^{-1} \prod_{k=1}^n \delta_p(y_k),$$

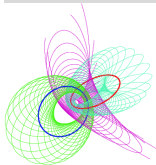
where y^T denotes transpose map of y .

Proposition

Let $x = (x_1, \dots, x_n)$, $\beta = (\beta_1, \dots, \beta_n)$ be two column vectors, and let $\alpha = (\alpha_{kl})$ be a nonsingular symmetric $n \times n$ matrix, where $x_k, \beta_k, \alpha_{kl} \in \mathbb{Q}_p$. Then

$$\begin{aligned} \int_{\mathbb{Q}_p^n} \chi_p(x^T \alpha x + \beta^T x) d^n x &= \Lambda_p(\alpha_1, \alpha_2, \dots, \alpha_n) |\det(2\alpha_{kl})|_p^{-\frac{1}{2}} \\ &\times \chi_p\left(-\frac{1}{4}\beta^T \alpha^{-1} \beta\right), \end{aligned}$$

where $\alpha_1, \alpha_2, \dots, \alpha_n$ are eigenvalues of the matrix α .



Proposition

Let $x = (x_1, x_2, \dots, x_n)$, $y = (y_1, y_2, \dots, y_n)$ be column vectors, and let $B = (B_{kl})$ be a nonsingular $n \times n$ matrix, where $x_k, y_k, B_{kl} \in \mathbb{Q}_v$. Then

$$\int_{\mathbb{Q}_v^n} \chi_p(y^T Bx) d^n x = |\det(B_{kl})|_p^{-1} \prod_{k=1}^n \delta_p(y_k),$$

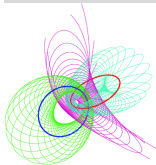
where y^T denotes transpose map of y .

Proposition

Let $x = (x_1, \dots, x_n)$, $\beta = (\beta_1, \dots, \beta_n)$ be two column vectors, and let $\alpha = (\alpha_{kl})$ be a nonsingular symmetric $n \times n$ matrix, where $x_k, \beta_k, \alpha_{kl} \in \mathbb{Q}_p$. Then

$$\begin{aligned} \int_{\mathbb{Q}_p^n} \chi_p(x^T \alpha x + \beta^T x) d^n x &= \Lambda_p(\alpha_1, \alpha_2, \dots, \alpha_n) |\det(2\alpha_{kl})|_p^{-\frac{1}{2}} \\ &\times \chi_p\left(-\frac{1}{4}\beta^T \alpha^{-1} \beta\right), \end{aligned}$$

where $\alpha_1, \alpha_2, \dots, \alpha_n$ are eigenvalues of the matrix α .



Quadratic Lagrangians

General quadratic Lagrangian has the form

$$L(\dot{q}, q, t) = \frac{1}{2} \dot{q}^T A \dot{q} + \dot{q}^T B q + \frac{1}{2} q^T C q + D^T \dot{q} + E^T q_k + \varepsilon$$

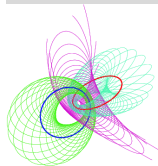
Euler-Lagrange equations:

$$A \ddot{q} + (\dot{A} + B - B^T) \dot{q} + (\dot{B} - C) q = E - \dot{D},$$

The solution of the above system has the form:

$$q = x(t) = F(t) \mathcal{C} + \xi(t),$$

where $F(t) = [f_{km}(t)] \in M_{n,2n}$ is a solutions of the corresponding system of homogeneous differential equations, $\mathcal{C} = [C_m] \in M_{2n,1}$ is the vector of constants, and $\xi(t) = [\xi_k(t)] \in M_{n,1}$ is a particular solution of the system.



Quadratic Lagrangians

General quadratic Lagrangian has the form

$$L(\dot{q}, q, t) = \frac{1}{2} \dot{q}^T A \dot{q} + \dot{q}^T B q + \frac{1}{2} q^T C q + D^T \dot{q} + E^T q_k + \varepsilon$$

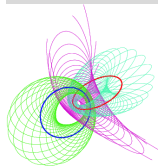
Euler-Lagrange equations:

$$A \ddot{q} + (\dot{A} + B - B^T) \dot{q} + (\dot{B} - C) q = E - \dot{D},$$

The solution of the above system has the form:

$$q = x(t) = F(t) \mathcal{C} + \xi(t),$$

where $F(t) = [f_{km}(t)] \in M_{n,2n}$ is a solutions of the corresponding system of homogeneous differential equations, $\mathcal{C} = [C_m] \in M_{2n,1}$ is the vector of constants, and $\xi(t) = [\xi_k(t)] \in M_{n,1}$ is a particular solution of the system.



General quadratic Lagrangian has the form

$$L(\dot{q}, q, t) = \frac{1}{2} \dot{q}^T A \dot{q} + \dot{q}^T B q + \frac{1}{2} q^T C q + D^T \dot{q} + E^T q_k + \varepsilon$$

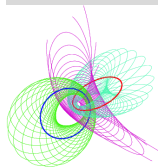
Euler-Lagrange equations:

$$A \ddot{q} + (\dot{A} + B - B^T) \dot{q} + (\dot{B} - C) q = E - \dot{D},$$

The solution of the above system has the form:

$$q = x(t) = F(t) \mathcal{C} + \xi(t),$$

where $F(t) = [f_{km}(t)] \in M_{n,2n}$ is a solutions of the corresponding system of homogeneous differential equations, $\mathcal{C} = [C_m] \in M_{2n,1}$ is the vector of constants, and $\xi(t) = [\xi_k(t)] \in M_{n,1}$ is a particular solution of the system.



Quadratic Lagrangians

General quadratic Lagrangian has the form

$$L(\dot{q}, q, t) = \frac{1}{2} \dot{q}^T A \dot{q} + \dot{q}^T B q + \frac{1}{2} q^T C q + D^T \dot{q} + E^T q_k + \varepsilon$$

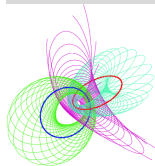
Euler-Lagrange equations:

$$A \ddot{q} + (\dot{A} + B - B^T) \dot{q} + (\dot{B} - C) q = E - \dot{D},$$

The solution of the above system has the form:

$$q = x(t) = F(t) \mathcal{C} + \xi(t),$$

where $F(t) = [f_{km}(t)] \in M_{n,2n}$ is a solutions of the corresponding system of homogeneous differential equations, $\mathcal{C} = [C_m] \in M_{2n,1}$ is the vector of constants, and $\xi(t) = [\xi_k(t)] \in M_{n,1}$ is a particular solution of the system.



General quadratic Lagrangian has the form

$$L(\dot{q}, q, t) = \frac{1}{2} \dot{q}^T A \dot{q} + \dot{q}^T B q + \frac{1}{2} q^T C q + D^T \dot{q} + E^T q_k + \varepsilon$$

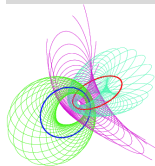
Euler-Lagrange equations:

$$A \ddot{q} + (\dot{A} + B - B^T) \dot{q} + (\dot{B} - C) q = E - \dot{D},$$

The solution of the above system has the form:

$$q = x(t) = F(t) \mathcal{C} + \xi(t),$$

where $F(t) = [f_{km}(t)] \in M_{n,2n}$ is a solutions of the corresponding system of homogeneous differential equations, $\mathcal{C} = [C_m] \in M_{2n,1}$ is the vector of constants, and $\xi(t) = [\xi_k(t)] \in M_{n,1}$ is a particular solution of the system.



Lemma

Imposing the boundary conditions $x'_k = x_k(t')$ and $x''_k = x_k(t'')$, the solution of the above system take the form

$$x_k(t) = \frac{1}{\Delta(t'', t')} \sum_{i=1}^{2n} \Delta_i(t'', t') f_{ki}(t) + \xi_k(t), \quad k = 1, 2, \dots, n.$$

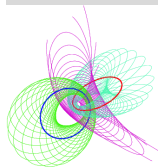
where $\Delta(t'', t') = \det \mathcal{F}$, and $\Delta_i(t'', t')$ has ordinary meaning.

Theorem

Let $\{f_{1j}, j = 1, 2, \dots, 2n\}$ be any linearly independent solutions of the resolvent equation for $x_1(t)$, then solutions $f_{km}(t)$ for $x_k(t)$, $k \neq 1$, are determined by the system and the following equality holds

$$\det \begin{bmatrix} F(t) \\ \dot{F}(t) \end{bmatrix} = \frac{\mathcal{D}}{\det A},$$

where \mathcal{D} is a non-zero constant, which could be chosen to be equal to 1.



Quadratic Lagrangians

Lemma

Imposing the boundary conditions $x'_k = x_k(t')$ and $x''_k = x_k(t'')$, the solution of the above system take the form

$$x_k(t) = \frac{1}{\Delta(t'', t')} \sum_{i=1}^{2n} \Delta_i(t'', t') f_{ki}(t) + \xi_k(t), \quad k = 1, 2, \dots, n.$$

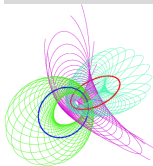
where $\Delta(t'', t') = \det \mathcal{F}$, and $\Delta_i(t'', t')$ has ordinary meaning.

Theorem

Let $\{f_{1j}, j = 1, 2, \dots, 2n\}$ be any linearly independent solutions of the resolvent equation for $x_1(t)$, then solutions $f_{km}(t)$ for $x_k(t)$, $k \neq 1$, are determined by the system and the following equality holds

$$\det \begin{bmatrix} F(t) \\ \dot{F}(t) \end{bmatrix} = \frac{\mathcal{D}}{\det A},$$

where \mathcal{D} is a non-zero constant, which could be chosen to be equal to 1.



Lemma

Imposing the boundary conditions $x'_k = x_k(t')$ and $x''_k = x_k(t'')$, the solution of the above system take the form

$$x_k(t) = \frac{1}{\Delta(t'', t')} \sum_{i=1}^{2n} \Delta_i(t'', t') f_{ki}(t) + \xi_k(t), \quad k = 1, 2, \dots, n.$$

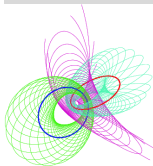
where $\Delta(t'', t') = \det \mathcal{F}$, and $\Delta_i(t'', t')$ has ordinary meaning.

Theorem

Let $\{f_{1j}, j = 1, 2, \dots, 2n\}$ be any linearly independent solutions of the resolvent equation for $x_1(t)$, then solutions $f_{km}(t)$ for $x_k(t)$, $k \neq 1$, are determined by the system and the following equality holds

$$\det \begin{bmatrix} F(t) \\ \dot{F}(t) \end{bmatrix} = \frac{\mathcal{D}}{\det A},$$

where \mathcal{D} is a non-zero constant, which could be chosen to be equal to 1.



Theorem

The general form of the action for classical trajectory $x(t)$ of a quadratic Lagrangian, for a particle being in point x' at the time t' and in position x'' at t'' , is

$$\bar{S}(x'', t''; x', t') = \frac{1}{2} x''^T \bar{A} x'' + x''^T \bar{B} x' + \frac{1}{2} x'^T \bar{C} x' + \bar{D}^T x'' + \bar{E}^T x' + \bar{\varepsilon},$$

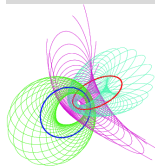
where $\bar{A} = [\bar{A}_{kl}]$, $\bar{B} = [\bar{B}_{kl}]$, $\bar{C} = [\bar{C}_{kl}]$, $\bar{D} = [\bar{D}_k]$, and $\bar{E} = [\bar{E}_k]$

$$\bar{A}_{kl} = \bar{A}_{kl}(t'', t') = \frac{\partial^2 \bar{S}_0}{\partial x''_k \partial x'_l}, \quad \bar{B}_{kl} = \bar{B}_{kl}(t'', t') = \frac{\partial^2 \bar{S}_0}{\partial x''_k \partial x'_l},$$

$$\bar{C}_{kl} = \bar{C}_{kl}(t'', t') = \frac{\partial^2 \bar{S}_0}{\partial x'_k \partial x'_l}, \quad \bar{D}_k = \bar{D}_k(t'', t') = \frac{\partial \bar{S}_0}{\partial x''_k},$$

$$\bar{E} = \bar{E}_k(t'', t') = \frac{\partial \bar{S}_0}{\partial x'_k}, \quad \bar{\varepsilon} = \bar{\varepsilon}(t'', t') = \bar{S}_0.$$

and subscript $_0$ in the classical action means that after performing derivatives of the $\bar{S}(x'', t''; x', t')$ one has to replace x'' and x' by $x'' = x' = 0$.



Theorem

The general form of the action for classical trajectory $x(t)$ of a quadratic Lagrangian, for a particle being in point x' at the time t' and in position x'' at t'' , is

$$\bar{S}(x'', t''; x', t') = \frac{1}{2} x''^T \bar{A} x'' + x''^T \bar{B} x' + \frac{1}{2} x'^T \bar{C} x' + \bar{D}^T x'' + \bar{E}^T x' + \bar{\varepsilon},$$

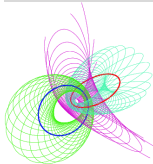
where $\bar{A} = [\bar{A}_{kl}]$, $\bar{B} = [\bar{B}_{kl}]$, $\bar{C} = [\bar{C}_{kl}]$, $\bar{D} = [\bar{D}_k]$, and $\bar{E} = [\bar{E}_k]$

$$\bar{A}_{kl} = \bar{A}_{kl}(t'', t') = \frac{\partial^2 \bar{S}_0}{\partial x''_k \partial x''_l}, \quad \bar{B}_{kl} = \bar{B}_{kl}(t'', t') = \frac{\partial^2 \bar{S}_0}{\partial x''_k \partial x'_l},$$

$$\bar{C}_{kl} = \bar{C}_{kl}(t'', t') = \frac{\partial^2 \bar{S}_0}{\partial x'_k \partial x'_l}, \quad \bar{D}_k = \bar{D}_k(t'', t') = \frac{\partial \bar{S}_0}{\partial x''_k},$$

$$\bar{E} = \bar{E}_k(t'', t') = \frac{\partial \bar{S}_0}{\partial x'_k}, \quad \bar{\varepsilon} = \bar{\varepsilon}(t'', t') = \bar{S}_0.$$

and subscript $_0$ in the classical action means that after performing derivatives of the $\bar{S}(x'', t''; x', t')$ one has to replace x'' and x' by $x'' = x' = 0$.



Path Integrals on real and p -adic spaces

The following formula holds

$$\begin{aligned} \mathcal{K}_p(x'', t''; x', t') &= \chi_p \left(-\frac{1}{h} \bar{S}(x'', t''; x', t') \right) \\ &\times \int_{y' \rightarrow 0, t'}^{y'' \rightarrow 0, t''} \chi_p \left(-\frac{1}{2h} \int_{t'}^{t''} \left(\dot{y}_k \frac{\partial}{\partial \dot{q}_k} + y_k \frac{\partial}{\partial q_k} \right)^2 L(\dot{q}, q, t) dt \right) \mathcal{D}y, \end{aligned}$$

where we used $y'' = y' = 0$, $S[x] = \bar{S}(x'', t''; x', t')$.

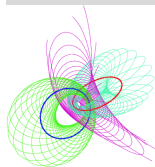
Theorem

(i1) $\mathcal{K}_p(x'', t''; x', t')$ has the form

$$\mathcal{K}_p(x'', t''; x', t') = N_p(t'', t') \chi_p \left(-\frac{1}{h} \bar{S}(x'', t''; x', t') \right),$$

where $N_p(t'', t')$ does not depend on end points x'' and x' .

$$(i2) \quad |N_p(t'', t')|_\infty = \left| \frac{1}{h^n} \det \frac{\partial^2}{\partial x_k'' \partial x_l'} \bar{S}_0(x'', t''; x', t') \right|_p^{\frac{1}{2}}.$$



The following formula holds

$$\begin{aligned} \mathcal{K}_p(x'', t''; x', t') &= \chi_p \left(-\frac{1}{h} \bar{S}(x'', t''; x', t') \right) \\ &\times \int_{y' \rightarrow 0, t'}^{y'' \rightarrow 0, t''} \chi_p \left(-\frac{1}{2h} \int_{t'}^{t''} \left(\dot{y}_k \frac{\partial}{\partial \dot{q}_k} + y_k \frac{\partial}{\partial q_k} \right)^2 L(\dot{q}, q, t) dt \right) \mathcal{D}y, \end{aligned}$$

where we used $y'' = y' = 0$, $S[x] = \bar{S}(x'', t''; x', t')$.

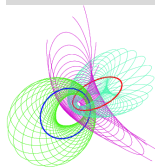
Theorem

(i1) $\mathcal{K}_p(x'', t''; x', t')$ has the form

$$\mathcal{K}_p(x'', t''; x', t') = N_p(t'', t') \chi_p \left(-\frac{1}{h} \bar{S}(x'', t''; x', t') \right),$$

where $N_p(t'', t')$ does not depend on end points x'' and x' .

$$(i2) \quad |N_p(t'', t')|_\infty = \left| \frac{1}{h^n} \det \frac{\partial^2}{\partial x_k'' \partial x_l'} \bar{S}_0(x'', t''; x', t') \right|_p^{\frac{1}{2}}.$$



The following formula holds

$$\begin{aligned} \mathcal{K}_p(x'', t''; x', t') &= \chi_p \left(-\frac{1}{h} \bar{S}(x'', t''; x', t') \right) \\ &\times \int_{y' \rightarrow 0, t'}^{y'' \rightarrow 0, t''} \chi_p \left(-\frac{1}{2h} \int_{t'}^{t''} \left(\dot{y}_k \frac{\partial}{\partial \dot{q}_k} + y_k \frac{\partial}{\partial q_k} \right)^2 L(\dot{q}, q, t) dt \right) \mathcal{D}y, \end{aligned}$$

where we used $y'' = y' = 0$, $S[x] = \bar{S}(x'', t''; x', t')$.

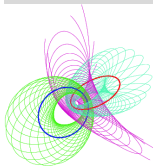
Theorem

(i1) $\mathcal{K}_p(x'', t''; x', t')$ has the form

$$\mathcal{K}_p(x'', t''; x', t') = N_p(t'', t') \chi_p \left(-\frac{1}{h} \bar{S}(x'', t''; x', t') \right),$$

where $N_p(t'', t')$ does not depend on end points x'' and x' .

$$(i2) \quad |N_p(t'', t')|_\infty = \left| \frac{1}{h^n} \det \frac{\partial^2}{\partial x_k'' \partial x_l'} \bar{S}_0(x'', t''; x', t') \right|_p^{\frac{1}{2}}.$$



Path integrals on real and p -adic spaces

The previous theorem implies the following relation

$$N_p(t'', t') = \left| \det \left(\frac{1}{h} \frac{\partial^2 \bar{S}_0(y'', t''; y', t')}{\partial y_k'' \partial y_l'} \right) \right|_p^{\frac{1}{2}} \mathcal{A}_p(t'', t'),$$

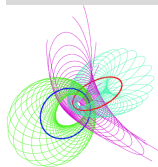
where $|\mathcal{A}_p(t'', t')|_\infty = 1$ and $\mathcal{A}_p(t'', t')$ remains to be determined explicitly.

Our expectations.

$$\int \mathcal{K}(x'', t''; x, t) \mathcal{K}(x, t; x', t') dx = \mathcal{K}(x'', t''; x', t'),$$

implies

$$\begin{aligned} & \left| \det \left(\frac{1}{h} \frac{\partial^2}{\partial y'' \partial y'} \bar{S}_0(y'', y) \right) \right|_p^{\frac{1}{2}} \left| \det \left(\frac{1}{h} \frac{\partial^2}{\partial y \partial y'} \bar{S}_0(y, y') \right) \right|_p^{\frac{1}{2}} \\ &= \left| \det \left(-\frac{C(t'', t) + A(t, t')}{h} \right) \right|_p^{\frac{1}{2}} \left| \det \left(\frac{1}{h} \frac{\partial^2}{\partial y'' \partial y'} \bar{S}_0(y'', y') \right) \right|_p^{\frac{1}{2}}, \end{aligned} \quad (1)$$



Path integrals on real and p -adic spaces

The previous theorem implies the following relation

$$N_p(t'', t') = \left| \det \left(\frac{1}{h} \frac{\partial^2 \bar{S}_0(y'', t''; y', t')}{\partial y_k'' \partial y_l'} \right) \right|_p^{\frac{1}{2}} \mathcal{A}_p(t'', t'),$$

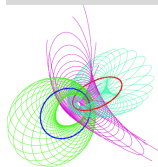
where $|\mathcal{A}_p(t'', t')|_\infty = 1$ and $\mathcal{A}_p(t'', t')$ remains to be determined explicitly.

Our expectations.

$$\int \mathcal{K}(x'', t''; x, t) \mathcal{K}(x, t; x', t') dx = \mathcal{K}(x'', t''; x', t'),$$

implies

$$\begin{aligned} & \left| \det \left(\frac{1}{h} \frac{\partial^2}{\partial y'' \partial y'} \bar{S}_0(y'', y) \right) \right|_p^{\frac{1}{2}} \left| \det \left(\frac{1}{h} \frac{\partial^2}{\partial y \partial y'} \bar{S}_0(y, y') \right) \right|_p^{\frac{1}{2}} \\ &= \left| \det \left(-\frac{C(t'', t) + A(t, t')}{h} \right) \right|_p^{\frac{1}{2}} \left| \det \left(\frac{1}{h} \frac{\partial^2}{\partial y'' \partial y'} \bar{S}_0(y'', y') \right) \right|_p^{\frac{1}{2}}, \end{aligned} \quad (1)$$



Path integrals on real and p -adic spaces

The previous theorem implies the following relation

$$N_p(t'', t') = \left| \det \left(\frac{1}{h} \frac{\partial^2 \bar{S}_0(y'', t''; y', t')}{\partial y_k'' \partial y_l'} \right) \right|_p^{\frac{1}{2}} \mathcal{A}_p(t'', t'),$$

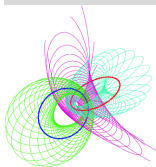
where $|\mathcal{A}_p(t'', t')|_\infty = 1$ and $\mathcal{A}_p(t'', t')$ remains to be determined explicitly.

Our expectations.

$$\int \mathcal{K}(x'', t''; x, t) \mathcal{K}(x, t; x', t') dx = \mathcal{K}(x'', t''; x', t'),$$

implies

$$\begin{aligned} & \left| \det \left(\frac{1}{h} \frac{\partial^2}{\partial y'' \partial y} \bar{S}_0(y'', y) \right) \right|_p^{\frac{1}{2}} \left| \det \left(\frac{1}{h} \frac{\partial^2}{\partial y \partial y'} \bar{S}_0(y, y') \right) \right|_p^{\frac{1}{2}} \\ &= \left| \det \left(-\frac{C(t'', t) + A(t, t')}{h} \right) \right|_p^{\frac{1}{2}} \left| \det \left(\frac{1}{h} \frac{\partial^2}{\partial y'' \partial y'} \bar{S}_0(y'', y') \right) \right|_p^{\frac{1}{2}}, \end{aligned} \quad (1)$$



Path integrals on real and p -adic spaces

The previous theorem implies the following relation

$$N_p(t'', t') = \left| \det \left(\frac{1}{h} \frac{\partial^2 \bar{S}_0(y'', t''; y', t')}{\partial y_k'' \partial y_l'} \right) \right|_p^{\frac{1}{2}} \mathcal{A}_p(t'', t'),$$

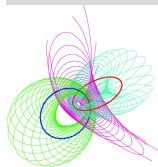
where $|\mathcal{A}_p(t'', t')|_\infty = 1$ and $\mathcal{A}_p(t'', t')$ remains to be determined explicitly.

Our expectations.

$$\int \mathcal{K}(x'', t''; x, t) \mathcal{K}(x, t; x', t') dx = \mathcal{K}(x'', t''; x', t'),$$

implies

$$\begin{aligned} & \left| \det \left(\frac{1}{h} \frac{\partial^2}{\partial y'' \partial y'} \bar{S}_0(y'', y) \right) \right|_p^{\frac{1}{2}} \left| \det \left(\frac{1}{h} \frac{\partial^2}{\partial y \partial y'} \bar{S}_0(y, y') \right) \right|_p^{\frac{1}{2}} \\ &= \left| \det \left(-\frac{C(t'', t) + A(t, t')}{h} \right) \right|_p^{\frac{1}{2}} \left| \det \left(\frac{1}{h} \frac{\partial^2}{\partial y'' \partial y'} \bar{S}_0(y'', y') \right) \right|_p^{\frac{1}{2}}, \end{aligned} \quad (1)$$



Path integrals on real and p -adic spaces

The previous theorem implies the following relation

$$N_p(t'', t') = \left| \det \left(\frac{1}{h} \frac{\partial^2 \bar{S}_0(y'', t''; y', t')}{\partial y_k'' \partial y_l'} \right) \right|_p^{\frac{1}{2}} \mathcal{A}_p(t'', t'),$$

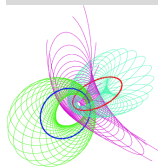
where $|\mathcal{A}_p(t'', t')|_\infty = 1$ and $\mathcal{A}_p(t'', t')$ remains to be determined explicitly.

Our expectations.

$$\int \mathcal{K}(x'', t''; x, t) \mathcal{K}(x, t; x', t') dx = \mathcal{K}(x'', t''; x', t'),$$

implies

$$\begin{aligned} & \left| \det \left(\frac{1}{h} \frac{\partial^2}{\partial y'' \partial y} \bar{S}_0(y'', y) \right) \right|_p^{\frac{1}{2}} \left| \det \left(\frac{1}{h} \frac{\partial^2}{\partial y \partial y'} \bar{S}_0(y, y') \right) \right|_p^{\frac{1}{2}} \\ &= \left| \det \left(-\frac{C(t'', t) + A(t, t')}{h} \right) \right|_p^{\frac{1}{2}} \left| \det \left(\frac{1}{h} \frac{\partial^2}{\partial y'' \partial y'} \bar{S}_0(y'', y') \right) \right|_p^{\frac{1}{2}}, \end{aligned} \quad (1)$$



Path integrals on real and p -adic spaces

The previous theorem implies the following relation

$$N_p(t'', t') = \left| \det \left(\frac{1}{h} \frac{\partial^2 \bar{S}_0(y'', t''; y', t')}{\partial y_k'' \partial y_l'} \right) \right|_p^{\frac{1}{2}} \mathcal{A}_p(t'', t'),$$

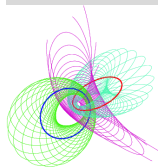
where $|\mathcal{A}_p(t'', t')|_\infty = 1$ and $\mathcal{A}_p(t'', t')$ remains to be determined explicitly.

Our expectations.

$$\int \mathcal{K}(x'', t''; x, t) \mathcal{K}(x, t; x', t') dx = \mathcal{K}(x'', t''; x', t'),$$

implies

$$\begin{aligned} & \left| \det \left(\frac{1}{h} \frac{\partial^2}{\partial y'' \partial y} \bar{S}_0(y'', y) \right) \right|_p^{\frac{1}{2}} \left| \det \left(\frac{1}{h} \frac{\partial^2}{\partial y \partial y'} \bar{S}_0(y, y') \right) \right|_p^{\frac{1}{2}} \\ &= \left| \det \left(-\frac{C(t'', t) + A(t, t')}{h} \right) \right|_p^{\frac{1}{2}} \left| \det \left(\frac{1}{h} \frac{\partial^2}{\partial y'' \partial y'} \bar{S}_0(y'', y') \right) \right|_p^{\frac{1}{2}}, \end{aligned} \quad (1)$$



Path integrals on real and p -adic spaces

The previous theorem implies the following relation

$$N_p(t'', t') = \left| \det \left(\frac{1}{h} \frac{\partial^2 \bar{S}_0(y'', t''; y', t')}{\partial y_k'' \partial y_l'} \right) \right|_p^{\frac{1}{2}} \mathcal{A}_p(t'', t'),$$

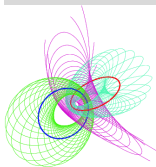
where $|\mathcal{A}_p(t'', t')|_\infty = 1$ and $\mathcal{A}_p(t'', t')$ remains to be determined explicitly.

Our expectations.

$$\int \mathcal{K}(x'', t''; x, t) \mathcal{K}(x, t; x', t') dx = \mathcal{K}(x'', t''; x', t'),$$

implies

$$\begin{aligned} & \left| \det \left(\frac{1}{h} \frac{\partial^2}{\partial y'' \partial y} \bar{S}_0(y'', y) \right) \right|_p^{\frac{1}{2}} \left| \det \left(\frac{1}{h} \frac{\partial^2}{\partial y \partial y'} \bar{S}_0(y, y') \right) \right|_p^{\frac{1}{2}} \\ &= \left| \det \left(-\frac{C(t'', t) + A(t, t')}{h} \right) \right|_p^{\frac{1}{2}} \left| \det \left(\frac{1}{h} \frac{\partial^2}{\partial y'' \partial y'} \bar{S}_0(y'', y') \right) \right|_p^{\frac{1}{2}}, \end{aligned} \quad (1)$$



$$\begin{aligned} & \chi_p \left(-\frac{1}{h} \left(\frac{1}{2} y''^T A(t'', t') y'' + y''^T B(t'', t') y' + \frac{1}{2} y'^T C(t'', t') y' \right) \right) \quad (2) \\ & = \chi_p \left(-\frac{1}{2h} (y''^T A(t'', t) y'' + y'^T C(t, t') y') \right) \chi_p \left(-\frac{1}{4} (z^T D^{-1} z) \right), \end{aligned}$$

where

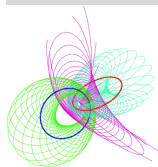
$$z = \frac{y''^T B(t'', t) + y'^T B^T(t, t')}{-h}$$

which imply the third one

$$\mathcal{A}_p(t'', t) \mathcal{A}_p(t, t') \Lambda_p(\alpha_1, \alpha_2, \dots, \alpha_n) = \mathcal{A}_p(t'', t'), \quad (3)$$

Let us mention here, that for $n = 1$ we have the following solution,

$$\mathcal{A}_p(t'', t') = \lambda_p \left(-\frac{1}{2h} \frac{\partial^2}{\partial y'' \partial y'} \bar{S}_0(y'', t''; y', t') \right).$$



$$\begin{aligned} & \chi_p \left(-\frac{1}{h} \left(\frac{1}{2} y''^T A(t'', t') y'' + y''^T B(t'', t') y' + \frac{1}{2} y'^T C(t'', t') y' \right) \right) \quad (2) \\ & = \chi_p \left(-\frac{1}{2h} (y''^T A(t'', t') y'' + y'^T C(t, t') y') \right) \chi_p \left(-\frac{1}{4} (z^T D^{-1} z) \right), \end{aligned}$$

where

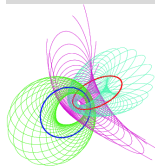
$$z = \frac{y''^T B(t'', t) + y'^T B^T(t, t')}{-h}$$

which imply the third one

$$\mathcal{A}_p(t'', t) \mathcal{A}_p(t, t') \Lambda_p(\alpha_1, \alpha_2, \dots, \alpha_n) = \mathcal{A}_p(t'', t'), \quad (3)$$

Let us mention here, that for $n = 1$ we have the following solution,

$$\mathcal{A}_p(t'', t') = \lambda_p \left(-\frac{1}{2h} \frac{\partial^2}{\partial y'' \partial y'} \bar{S}_0(y'', t''; y', t') \right).$$



$$\begin{aligned} & \chi_p \left(-\frac{1}{h} \left(\frac{1}{2} y''^T A(t'', t') y'' + y''^T B(t'', t') y' + \frac{1}{2} y'^T C(t'', t') y' \right) \right) \quad (2) \\ & = \chi_p \left(-\frac{1}{2h} (y''^T A(t'', t') y'' + y'^T C(t, t') y') \right) \chi_p \left(-\frac{1}{4} (z^T D^{-1} z) \right), \end{aligned}$$

where

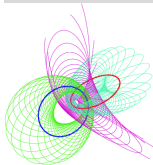
$$z = \frac{y''^T B(t'', t) + y'^T B^T(t, t')}{-h}$$

which imply the third one

$$\mathcal{A}_p(t'', t) \mathcal{A}_p(t, t') \Lambda_p(\alpha_1, \alpha_2, \dots, \alpha_n) = \mathcal{A}_p(t'', t'), \quad (3)$$

Let us mention here, that for $n = 1$ we have the following solution,

$$\mathcal{A}_p(t'', t') = \lambda_p \left(-\frac{1}{2h} \frac{\partial^2}{\partial y'' \partial y'} \bar{S}_0(y'', t''; y', t') \right).$$



$$\begin{aligned} \chi_p \left(-\frac{1}{h} \left(\frac{1}{2} y''^T A(t'', t') y'' + y''^T B(t'', t') y' + \frac{1}{2} y'^T C(t'', t') y' \right) \right) & \quad (2) \\ = \chi_p \left(-\frac{1}{2h} (y''^T A(t'', t') y'' + y'^T C(t, t') y') \right) \chi_p \left(-\frac{1}{4} (z^T D^{-1} z) \right), \end{aligned}$$

where

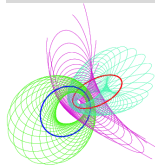
$$z = \frac{y''^T B(t'', t) + y'^T B^T(t, t')}{-h}$$

which imply the third one

$$\mathcal{A}_p(t'', t) \mathcal{A}_p(t, t') \Lambda_p(\alpha_1, \alpha_2, \dots, \alpha_n) = \mathcal{A}_p(t'', t'), \quad (3)$$

Let us mention here, that for $n = 1$ we have the following solution,

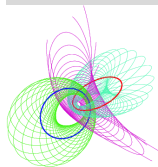
$$\mathcal{A}_p(t'', t') = \lambda_p \left(-\frac{1}{2h} \frac{\partial^2}{\partial y'' \partial y'} \bar{S}_0(y'', t''; y', t') \right).$$



Expectations

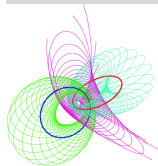
We expect the following solution,

$$\mathcal{A}_p(t'', t') = \lambda_p \left(-\frac{1}{2h} \det \left| \frac{\partial^2}{\partial y'' \partial y'} \bar{S}_0(y'', t''; y', t') \right| \right).$$



We expect the following solution,

$$\mathcal{A}_p(t'', t') = \lambda_p \left(-\frac{1}{2h} \det \left| \frac{\partial^2}{\partial y'' \partial y'} \bar{S}_0(y'', t''; y', t') \right| \right).$$



**THANK YOU FOR
YOUR ATTENTION !!!**

